

ULT Mechatronics Engineering

Subjects Modules for S5

Semester 1 Year 3

U5.1: Electronics Electrotechnics 5 EE 5 U5.1.1: Analysis & Control of Complex Systems

Module designation	Electronics Electrotechnics 5 EE 5
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.1
Subtitle, if applicable	
Courses, if applicable	Analysis & Control of Complex Systems
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Dr Emna RABHI
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	Lecture, 21 hours Classroom Lecture/ Semester
Workload	Total 51hours/ Semester (30 hours of Self Study)
Credit points	2
Requirements according to the examination regulations	 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Recommended prerequisites	Calculus, Math for Engineering 1 & 2, Linear Systems Analysis, Automatic Control
Module objectives/intended learning outcomes	 Objectives: At the end of this course, the student will be able to: 1- Present the foundations of the analysis and synthesis of the control law for nonlinear systems. 2- Determine the amplitude and frequency of limit cycles by the first harmonic method. 3- Determine the stability, in the sense of Lyapunov, for the points of equilibrium, and the associated theorems, property of passivity and its consequences allowing to guarantee the stability of a linear system comprising a non-linearity of the static type.

Content	Chapter 1: NON-LINEAR CONTINUOUS CONTROLS ANALYSIS
content	1- General Introduction
	2- Different types of non-linearity
	3- Study of the linearity domain of a system
	4- The phenomenon of saturation
	5- Determination of the linearity domain of a controlled
	system
	6- Characteristics of some nonlinear organs
	7- All-or-nothing and Hysteresis systems
	8- Complex features
	9- Separable non-linear drives
	5- Separable non inical drives
	Chapter 2: Separable System Study using the first harmonic method
	1- Principle
	2- Equivalent complex gain
	3- Concept of critical place
	4- Example
	5- First harmonic method
	6- Method of approximate calculation of the equivalent
	complex gain
	Chapter 3: Nonlinear Systems Stability
	1- Generalized transfer function
	2- Principle of the study
	3- Example
	5- Example
	Chanter A. Cunkin's Legue Study Method
	Chapter 4: Cypkin's Locus Study Method
	1- Principle
	2- Example
	Chapter 5: Phase plan method
	1- Principle
	2- Tracing the trajectories
	 Analysis of trajectories and system diagnosis
Study and examination requirements and forms of examination	Written Mid-Term Exam (40%) + Written Final Exam (60%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online
	(Moodle ULT)
	Video projection
Reading list	 Philippe Müllhaupt Introduction à l'analyse et à la commande des systèmes non linéaires
	2- D Normand-Cyrot, Collectif, A Fossard, SYSTEMES NON LINEAIRES. Tome 3, Commande
	3- HANUS Raymond, Automatique avancée 2 : commande des
	systèmes non linéaires.

U5.1: Electronics Electrotechnics 5 EE 5
U5.1.2: industrial Programmable Automated

Module designation	Electronics Electrotechnics 5: EE5
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.1
Subtitle, if applicable	
Courses, if applicable	Industrial Programmable Automated API
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Dr. Mohamed Aymen Slim
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	Lecture, 21 hours Classroom Lecture/ Semester
	42 hours for Workshop in Lab / semester
Workload	Total 84 hours/ Semester (21 hours of Self Study)
Credit points	3
Requirements according to the	- Minimum attendance rate: 80% of the total contact hours
examination regulations	>20 % of nonattendance = elimination for exams
Recommended prerequisites	Logic functions ; Sensors-Actuators; Industrial Control 1
Module objectives/intended learning outcomes	 Objectives: 1. Understand Structured Programming using GRAFCET (GEMMA Interface) 2. Learn and practices structured programming on Siemens PLC - S7-1200 PLC under TIAPortal 3. Understand the utility of the programming of Analog I / O and other resources on the PLC 4. Understand the PLC Supervision (SCADA) in real application

Content	
	Lecture & Lab Workshop
	Part 1: Industrial Programmable Logic Controller (PLC)
	1- Structure of an automated production system
	2- Sensors-Actuators
	3-External API architecture
	4- Internal architecture and concept of PLC scanning
	Part 2: Programming of PLC
	1- Basic concept of PLC programming
	2- Introduction to PLC programming language (Ladder diagram)
	3- Time delay block- Counter block
	4- Application exercises
	Part 3: Functional Graphic of Steps / Transitions Control
	GRAFCET (or SFC)
	1- Basic concept of GRAFCET (or SFC)
	2- OR and AND referrals for GRAFCET
	3- Logical equation of a step
	 4- Macro step and encapsulation 5- Application exercises (GRAFCET -PLC programming)
	5- Application exercises (GRAFCET-PLC programming)
	Part 4: GRAFCET and GEMMA
	1- Description of GEMMA Environment
	2- Structured programming using GRAFCET
	3-Practical application Siemens PLC S7-1200
	Part 5: Structured programming of PLC
	1- Basic concept of structured PLC programming 2- OB, FB, FC, DB Blocks - PLC S7-1200
	3- Practical application on Siemens PLC S7-1200 PLC
	Part 6: PLC Analog Inputs / Outputs
	1- Description of PLC Analog I / O
	2- Practical application Analog I / O - S7-1200
	3- Practical application: Clock Memory bits, fast count inputs
	Part 7: PLC Supervision (SCADA)
	1- Basic concept on the supervision of industrial
	processes 2- Human Machine Interface (HMI) for PLC
	supervision
	3- Practical applications- HMI (supervision) PLC S7-1200- WINCC Interface
	**Abbreviations in French & English are presented to Students:
	1. GRAFCET : GRAphe Fonctionnel de Commande Etapes
	Transitions
	Equivalent: *SFC : Sequential Function Chart
	2. API: Asservissement des Processus Industriel
	Equivalent : PLC : Programmable Logic Controller for Industry
	3. GEMMA: Guide d'Etude des Modes de Marche et d'Arrêt
	It is Graphic Interface

	 4. SCADA: Supervisory Control And Data Acquisition 5. HMI : Human Machine Interface **GRAFCET & GEMMA Tools Developed by ADEPA France : National Agency for the Development of Productics Applied to Industry
Study and examination requirements and forms of examination	Written Mid-Term Exam (25%) + Practical Workshop and project Oral presentation(25%)+Written Final Exam (50%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Workshop handbook + Siemens S7-1200 PLC Video projection
Reading list	 - AUTOMATES PROGRAMMABLES INDUSTRIELS ; WILLIAM BOLTON ; EDITION DUNOD (2015) - LE GRAFCET ; SIMON MORENO, EDMOND PEULOT ; EDITION EDUCALIVRE (2003)

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U5.2: Mechanics 5		
U5.2.1: Finite Element Method & Abaqus		

Mechanics 5
Year 3, Semester 1
U5.2
Finite Element Method & Abaqus
Semester 5
Dr Emna RABHI
Dr. Amine KAROUI
French
Compulsory module ,
Lecture, 21 hours Classroom Lecture/ Semester 21 hours for Workshop in Lab / semester
Total 84 hours/ Semester (42 hours of Self Study)
3
 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Math (Matrix), Continuum Mechanics, Linear systems
 Objectives: 1. Introduction to the Finite Element Method FEM 2. Understand application of FEM through some applications 3. Learn using ABAQUS tools for simulation an of some structure application and result analysis

Contout	Chapter I. Introduction to the Finite Element Method FEM
Content	1. Presentation of numerical calculation methods
	2. Presentation of the Elements Method Concept in implicit
	calculation
	2.1. Description of discretization (mesh)
	2.2. Degree of Freedom Description (nodal values unknowns)
	2.3. Interpolation Matrices Definition
	2.4. Construction of the elementary stiffness matrixes
	2.5. Assembly principle of elementary stiffness matrices in
	order to arrive at the global matrix
	2.6. Notions of boundary conditions and their consideration in
	calculations.
	2.7. Expression of the global force vector and its assembly.
	2.8. Expression of the linear system to be solved.
	Chapter II. Application of the Finite Element Method to
	traction-compression problem
	1. Developments and determination of interpolation functions
	2. Expression of the elementary stiffness matrix from mechanical
	computation
	 Construction of the total matrix of rigidity (assembly) Principle of discretization of distributed loadings.
	5. Expression of the global force vector and its assembly.
	6. Resolution of the linear problem after reduction by the
	boundary conditions.
	Chapter III. Application of FEM to the resolution of plane
	bending beam problems.
/	 Developments and determination of interpolation functions Expression of the elementary stiffness matrix from the
	potential energy of elastic strain
	3. Construction of the total matrix of rigidity (assembly)
	4. Principle of discretization of distributed loadings.
	5. Expression of the global force vector and its assembly.
	6. Resolution of the linear problem after reduction by the
	boundary conditions.
	Chapter IV. Application of FEM to solving thermal problems
	(through a composite wall)
	1. Expressions of the different forms of heat exchange, thermal
	equilibrium equation
	2. Development of the variational formulation (transition from
	the strong formulation to the weak formulation).
	3. Developments and determination of interpolation functions.
	4. Expression of the elementary stiffness matrix starting from the variational formulation.
	5. Construction of the total matrix of rigidity (assembly).
	6. Expression of the various thermal force vectors and assembly of the global vector.
	7. Resolution of the linear problem after reduction by the
	boundary conditions.

	Practical workshop in Laboratory
	TP 1: Getting started - Philosophy of finite element calculation codes - Modelling approach of a physical problem on ABAQUS - Introduction to ABAQUS CAE, features, menus, modules, etc.
	 TP2: Study of a lattice structure Geometry drawing on Abaqus Introduction of the various calculation parameters Taking into account the boundary conditions Meshing and problem solving
	 Results analysis TP3: Study of a tensile test specimen 2D modelling of the test specimen on Abaqus Problem setting Division of the test specimen into several subdomains in order to make several meshes Solving the problem and generating specific results
	 TP4: Study of deformations in a 3D part 3D modelling of the part on ABAQUS Problem setting Mesh and resolution Results analysis
	 TP5: Study of the linear impact on a plate Modelling of the plate and the cylinder impact Modelling of the problem (interaction between parts) Mesh and resolution Study of the results
Study and examination requirements and forms of examination	Written Mid-Term Exam (25%) + Practical Workshop Exam(25%)+ Written Final Exam (50%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Workshop Handbook in Lab
Reading list	 Video projection -An introduction to the finite element method (3rd edition), by J N REDDY -Méthode des éléments finis : flexion des poutres a plan moyen, YVES DEBARD (cours) -Méthode des éléments finis en thermique et en thermomécanique, L. CHAMPANEY (cours) -Les éléments finis : de la théorie à la pratique, André Fortin Université Laval et André Garon École Polytechnique de Montréal. (Cours) -Dassault Systems Abaqus CAE website: 3ds.com

U5.2: Mechanics 5 U5.2.2: Advanced Robotics

Module designation	Mechanics 5
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.2
Subtitle, if applicable	
Courses, if applicable	Advanced Robotics
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Dr. Amjed MOUELHI
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	Workshop 21 hours in Lab/ Semester
Workload	Total 51 hours/ Semester (30 hours of Self Study)
Credit points	2
Requirements according to the examination regulations	 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Recommended prerequisites	Robotics 1 & 2, Robot Programming, Automatic Control, Solid Mechanics, Math
Module objectives/intended learning outcomes	 Objectives: 1. This last Workshop will enable students to practice easily the Robot Manipulator 2. Learn to solve movement planning problems of the robot 3. Command the Robot Manipulator to perform a specific task through various examples during the Workshop
\checkmark	

Content	Chapter 1- Introduction to nonlinear control of manipulator
	 Introduction The Control Problem For Manipulators Properties of the Dynamic Model Lyapunov stability analysis
	Chapter 2 Position control of manipulator
	 Introduction Proportional Control plus Velocity Feedback and PD Control PD Control with Gravity Compensation Chapitre 3 : Robot control by Pre-computed Torque-I Chapitre 4: Robot control by Pre-computed Torque -II Chapitre 5: Force control of Robot Manipulator Chapitre 6: Robot Manipulator Control by sliding modes
Study and examination requirements and forms of examination	Continuous Assessment 40% (Report for each workshop required) +Semester Workshop Exam 60 %
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Video projection
Reading list	 Robot modelling and control : M.W.Spong Introduction to Robotics: Mechanics and Control (3rd Edition) 3rd Edition John J. Craig

US.3.1: Reliability & Safety of Mechatronics systems		
Module designation	Mechatronic Elements 5	
Module level, if applicable	Year 3, Semester 1	
Code, if applicable	U5.3	
Subtitle, if applicable		
Courses, if applicable	Reliability & Safety of Mechatronics systems	
Semester(s) in which the module is taught	Semester 5	
Person responsible for the module	Dr Emna RABHI	
Lecturer	Dr. RAOUADI Mohamed Haithem	
Language	French	
Relation to curriculum	Compulsory module ,	
Type of teaching, contact hours	Lecture, 21 hours Classroom Lecture/ Semester	
Workload	Total 42hours/ Semester (30 hours of Self Study)	
Credit points	2	
Requirements according to the	- Minimum attendance rate: 80% of the total contact hours	
examination regulations	>20 % of nonattendance = elimination for exams	
Recommended prerequisites	Electrical	
Module objectives/intended learning outcomes	 Objectives: 1. Characterize the concepts of the dependability of a system. 2. Identify the methods and tools applicable to the analysis of the dependability of a system. 3. Apply Reliability calculation and control techniques when designing a system. 	

U5.3: Mechatronic Elements 5 U5.3.1: Reliability & Safety of Mechatronics systems

Content	 Chapter 1. Reliability and Company Global Optimization 1. Introduction 2. General and definitions 3. Reliability and reliability typology 4. Reliability models and laws
	 Chapter 2. Reliability Estimation Using Probability Theory 1. Scenario 2. The exponential law 3. The normal law 4. Weibull's law 5. Estimation by observation 6. Graphic adjustment of the Weibull law
	 7. Reliability Improvement Methods Chapter 3. Markov chain Discrete time Markov chain Continuous-time Markov chain Chapter 4. Maintainability indicators
	Chapter 5. Cost of non-availability
Study and examination requirements and forms of examination	Written Mid-Term Exam (40%) + Written Final Exam (60%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Video projection
Reading list	 VILLEMEUR Sûreté de Fonctionnement de Systèmes Industriels, Editions Eyrolles G. ZWINGELSTEIN Diagnostic des Défaillances : Théorie et Pratique pour les Systèmes Industriels, Editions Hermes JC FRANCASTEL le fond de la baignoire : chez Dunod I. BAZOVSKY Théorie et Pratique de la Sûreté de Fonctionnement, Editions Dunod M. CORAZZA Techniques Mathématiques de la Fiabilité Prévisionnelle Cepadues-Editions F. MONCHY, Maintenance méthodes et organisations, Dunod, 2003 Management de la Maintenance 2e édition, Editeur : Dunod ; 2008 2e édition

	u Maintenance Management System Civilyis
Module designation	Mechatronic Elements 5
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.3
Subtitle, if applicable	
Courses, if applicable	Computerized Maintenance Management System CMMS
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Dr. Riheb Mechmech
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	21 hours for Workshop in Lab/ semester 21 hours for Prjects
Workload	Total 84hours/ Semester (42 hours of Self Study)
Credit points	3
Requirements according to the examination regulations	 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Recommended prerequisites	Industrial maintenance
Module objectives/intended learning outcomes	 Objectives: 1. Understand the different basic aspects of industrial maintenance (preventive maintenance, corrective maintenance, reliability, etc.) 2. Understand CMMS Computerized Maintenance Management System 3. Practices in Lab using OptiMaint tools to go through all aspect of the management system using the three workshop sessions

U5.3: Mechatronic Elements 5 U5.3.2: Computerized Maintenance Management System CMMS

Content	
	Course highlights:
	Preventive maintenance.
	Corrective maintenance.
	Reliability of systems.
	 Failure Mode Effects and Criticality Analysis
	Total productive maintenance.
	Workshops (in Lab):
	TP1: EQUIPMENT AND PERSONNEL MANAGEMENT
	1- Creation of equipment.
	2- Creation of organs.
	3- Creation of stakeholders.
	4- Creation of articles.
	TP2: STOCKS AND PURCHASES MANAGEMENT:
	1- Creation of suppliers.
	2- Stock Inventory management.
	3- Purchasing management.
	TP3: INTERVENTIONS MANAGEMENT
	1- Corrective interventions.
	2- Preventive interventions.
	Projects topics:
	 TPM (total productive maintenance).
	FMECA study.
	Maintenance dashboard.
	Development of a CMMS
Study and examination	100% practical evaluation (Workshop) +Project evaluation
requirements and forms of	(Presentation+ Report)
examination	
Media employed	Workshop Handbook in Lab
	Video projection
	OPTIMAINT Software User Guideline

U5.4: Computer Science U5.4.1: Artificial Intelligence (AI)

Module designation	Computer Science
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.4
Subtitle, if applicable	
Courses, if applicable	Artificial Intelligence (AI)
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Dr Farah CHENCHAH
Language	English
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	Lecture, 21 hours Classroom Lecture/ Semester
Workload	Total 51hours/ Semester (30 hours of Self Study)
Credit points	2
Requirements according to the examination regulations	 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Recommended prerequisites	Algorithmic, Object Oriented Programming, Python, Linear Algebra
Module objectives/intended learning outcomes	 Objectives: Know the foundations of artificial intelligence Understand the characteristics and basic techniques used for artificial intelligence. Master the AI development history, the Huawei Ascend AI system, the full-stack all-scenario AI strategy and algorithms related to traditional machine learning and deep learning. Learning Outcomes Learning Outcomes: Students will be able to : Build, train, and deploy neural networks by using development frameworks TensorFlow and MindSpore. Be a developer, product manager, technical support, and other AI positions. Obtain the HCIA-AI (H13-311) certification

	Chapter 1 Introduction to Artificial Intelligence Al
Content	Chapter 1. Introduction to Artificial Intelligence AI
	1.1. History
	1.2. Definition
	1.3. Future of Artificial Intelligence
	Chapter 2. Python
	2.1. What is Python
	2.2. Basic types
	2.3. Conditional and iterative structures
	2.4. Functions
	2.5. Regular expressions
	2.6. File manipulation
	Chapter 3. The Basics of Mathematics
	3.1. Linear algebra
	3.2. Probability theory
	3.3. Information theory
	3.4. Numerical calculation
	Chapter 4. Machine Learning and deep learning
	4.1. Machine Learning
	4.2. Deep Learning
	Chapter 5. Development Framework and Platform For IA
	5.1. Tensor Flow
	5.2. Huawei AI: MindSpore
	5.3. Huawei AI : Atlas
	5.4. Huawei AI : HiAI
	5.5. HUAWEI CLOUD EI
	Chapter 6. Comprehensive AI Experiment
	6.1. Machine Learning Experiment
	6.2. Mainstream Development Framework and
	Deep Learning Experiment
Study and examination requirements and forms of examination	Written Mid-Term Exam (40%) + Written Final Exam (60%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT)
	Video projection
Reading list	 S. Russell And P. Norvig, Artificial Intelligence: A Modern Approach, Prentice Hall, 2002 J-G. Ganascia, L'intelligence Artificielle. Flammarion, 1993 I. Bratko, Programmation En Prolog Pour L'intelligence Artificielle, 2001
	 4. J. Alliot Et T. Schiex, Intelligence Artificielle Et Informatique Theorique, Cepadues Editions, 1993 5. HCIA-AI Course (Huawei ICT Academy online)

U5.4: Computer Science U5.4.2 Data Analysis

	5.4.2 Data Analysis Computer Science
Module designation	
Module level, if applicable	3 nd year, Semester 1
Code, if applicable	U5.4
Subtitle, if applicable	-
Courses, if applicable	Data Analysis
Semester (s) in which the module is taught	-Semester 5
Person responsible for the module	Dept. Head Dr Emna Rabhi
Lecturer	Dr. Marwa HASNI
Language	French
Relation to curriculum	Professional module (compulsory)
Type of teaching, contact hours	21 hours Lecture
	21 Workshop
Workload	Total 51 Hours (9 Hours of Self Study)
Credit points	2
Requirements according to the examination regulations	- Minimum attendance rate: 80% of the total contact hours
	>20 % of nonattendance = elimination for exams
Recommended prerequisites	Programming
Module objectives/intended learning outcomes	 Objectives: Familiarize students with data modelling and analysis using specific methods Learning Outcomes: Students will be able to : Model an industrial problem using multiple regression tools Master key tests to assess the robustness of the proposed models (confidence interval, correlation between variables) Study and apply CP, AHP and Electre multi-criteria analysis methods to address decision support issues. Provide an interpretation based on the models developed to assist in decision-making on the alternative solution(s) to the problem being studied Master the use of Microsoft Excel and Python for regression data analysis methods: ACP and AFC using SPSS and python

Content	 Chapter 1: Introduction to Data Analysis Reminder on key concepts of descriptive database statistics Modelling an industrial problem by simple linear regression Chapter 2: Multiple linear regression Modelling (matrix calculation to estimate parameters) Application on Excel and python Assessment of the robustness of regression models (development of tolerance intervals, correlation study) Chapter 3: Introduction to Multi-criteria Analysis The AHP method The Electre method 3/Applications Chapter 4: Principle Component Analysis Concept and implementation steps Implementation on python, SPSS + Interpretation Chapter 5: Correspondence Factor Analysis Concept and implementation steps Implementation on python + Interpretation Chapter 6: Methods of classification Hierarchical classification (Concept and implementation steps) Non-hierarchical classification (Concept and implementation steps) Implementation on python + Interpretation
Study and examination requirements and forms of examination	Written Mid-term Exam (25%) + Workshop(oral presentation) (25%)+Written Final Exam (50%)
Media employed	Course Material (Hard/ Soft copy) for Classroom + activity booklet Video projection
Reading list	Ref.1 : Benzécri, JP., & Coll., (1980). L'analyse des données, Tome 2 : l'analyse des correspondances, Dunod Ref 2 : Benzécri, JP., (1982). Histoire et préhistoire de l'analyse des données, Dunod Ref 3 : Benzécri, JP., Benzécri F., (1980). Pratique de l'analyse des données, Tome 1 : Analyse des correspondances. Exposé élémentaire, Dunod

U5.4 Computer Science

U5.4.3 Computer Vision

US.4.3 Computer vision		
Module designation	Computer Science	
Module level, if applicable	3 rd year of mechatronic engineering	
Code, if applicable	U5.4	
Subtitle, if applicable	-	
Courses, if applicable	Computer vision	
Semester (s) in which the	Semester 5	
module is taught		
Person responsible for the	Dept. Head Dr Emna Rabhi	
module		
Lecturer	Dr Farah Chenchah	
Language	French	
Relation to curriculum	Compulsory module ,	
Type of teaching, contact	21 hours Workshop / projects	
hours		
Workload	Total 51hours/ Semester (30 hours of Self Study)	
Credit points	2	
Requirements according	- Minimum attendance rate: 80% of the total contact hours	
to the examination	>20 % of nonattendance = elimination for exams	
regulations		
Recommended	1. Mathematics: Knowledge of and ability to use calculus, analytical	
prerequisites	geometry, linear algebra and probability theory.	
prerequisites	2. Programming: Ability to program in Python.	
	3. Other Courses: There are no specific pre-requisite courses. In	
	particular, courses in Al, Machine Learning, Deep Learning, Computer	
	Vision and Image Processing are not required.	
Module	This course provides an introduction to computer vision, including	
objectives/intended	fundamentals of image formation, camera imaging geometry, feature	
learning outcomes	detection and matching, stereo, motion estimation and tracking,	
	image classification, scene understanding, and deep learning with	
	neural networks.	
	Objectives :	
	Upon completion of this course, students will:	
	• Bo familiar with both the theoretical and practical aspects of	
	 Be familiar with both the theoretical and practical aspects of computing with images; 	
	 Have described the foundation of image formation, 	
	measurement, and analysis;	
	 Have implemented common methods for robust image metabling and alignment. 	
	matching and alignment;	
	 Understand the geometric relationships between 2D images and the 3D world; 	
	 Have gained exposure to object and scene recognition and categorization from images; 	
	 Grasp the principles of state-of-the-art deep neural networks; 	
	and Developed the practical skills necessary to build computer vision applications.	

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Content	 Introduction :Background, requirements and issues, human vision
	2. Image formation: geometry and photometry
	Geometry, photometry (brightness and color), quantization,
	camera calibration
	3. Image segmentation and Feature Extraction
	Various methods of image segmentation, edge detection,
	object proposals, SIFT features
	4. Multi-view Geometry
	Shape from stereo and motion, feature matching, surface
	fitting, Active ranging
	5. Object Recognition: Traditional Methods
	Hog/SIFT features, Bayes classifiers, SVM classifiers
	6. Introduction to Neural Networks
	Artificial neural networks, loss functions, backpropagation and
	SGD, Batch Normalization
	7. Object Recognition: Deep Learning Methods
	Image classification, object detection and semantic
	segmentation, adversarial attacks. Various neural network
	architectures, visualization techniques.
	8. Motion analysis and Activity Recognition
	Motion detection and tracking, Inference of human activity
	from image sequences
	9. Selected Topics
	Examples: Face recognition, Image grounding, Visual question
	answering
	answering
Study and examination	Evaluation of report, and oral presentation (100%)
requirements and forms	
of examination	
Media employed	Course Material (Hard/ Soft copy) for Classroom
	Video projection
Reading list	1. "Computer Vision: A Modern Approach", D. Forsyth and J.
	Ponce, 2010.
	2. "Deep Learning: Algorithms and Applications", I. Goodfellow, Y.
	Bengio and A. Courville, 2017 (online version available at no
	cost for personal use).
	3. "A Guide to Convolutional Neural Networks for Computer
	Vision", S. Khan, H. Rahmani, S.Shah and M. Bennamoun, 2018
	(online version available from a USC account).

List of Electives:

Elective Unit 1: lot Advanced	Elective Module 1 : Cloud & Security
	Elective module 2 : IOT Chain Implementation
Elective Unit 2: Automotive	Elective module 1 Vehicle Embedded Systems ENG
embedded system	Elective module 2 : Vehicle Autonomous Systems ENG

U5.5 Electives Unit 1: IOT ADAVANCED

U5.5.1 Cloud & Security

Module designation	IOT Advanced
Module level, if applicable	2 nd year of Mechatronics engineering
Code, if applicable	U4.4
	04.4
Subtitle, if applicable	
Courses, if applicable	Cloud & Security
Semester (s) in which the module is taught	-Semester 5
Person responsible for the module	Dept. Head Dr Emna Rabhi
Lecturer	M Ahmed Boughanmi
Language	French
Relation to curriculum	Electives Professional module
Type of teaching, contact hours	21 course
	21 Workshop / Projects
Workload	Total 84 Hours (42 Hours of Self Study)
Credit points	3
Requirements according to the	- Minimum attendance rate: 80% of the total contact hours
examination regulations	>20 % of nonattendance = elimination for exams
Recommended prerequisites	
Module objectives/intended	Objectives:
learning outcomes	Introductory course in cloud computing addressing both the challenges and existing solutions on the market and also the practical aspects of cloud computing security, both in terms of identifying and assessing risks
	Learning Outcomes:
	students will be able to:
	 Understand the advantages and challenges of a total or part of a cloud computing strategy.
	 Understand how to introduce and manage a Cloud Computing project in a company
	-Ensure information security in cloud computing

Content	CHAPTER 1 : What is Cloud Computing ?
	- Definitions: type Technology Cycle
	- Cloud Computing Characteristics
	- Cloud Computing Service Models
	- Cloud Computing Deployment Models •
	CHAPTER 2: Cloud Computing Framework
	- Global Framework (public cloud, private cloud, hybrid
	cloud,)
	- Cloud Computing Enablers
	- Cloud Computing Assets
	- Cloud Computing Challenges - Issues
	CHAPTER 3 : Cloud Computing Security
	- Fact & Figures
	- Security Advantages & Issues
	- Virtualization Risks
	CHAPTER 4 : Cloud Computing Market Overview
	- Main laaS Offers
	- Main Paas Offers
	- Main SaaS Offers § Other Offers
	CHAPTER 5 : Cloud Computing Project Management
	- Project Scenarios
	- Points of Attention
	- IT department roles
	CHAPTER 6: Basic concept of information security
	-Security of virtual environments
	-The security of network access to the Cloud
	-Cloud Computing Security according to ENISA - Control cloud security
	Practical Project are listed year by the Teacher.
Study and examination	Evaluation of report, and oral presentation (100%)
requirements and forms of	
examination	
	Course Material (Hard/ Soft copy) for Classroom & Online
Media employed	(Moodle ULT)
	- M. L. Badger, T. Grance, R. Patt-Corner, and J. M. Voas.
	(2012, May) Cloud Computing
	Synopsis and Recommendations.
	-P. Mell and T. Grance. (2009, July) The NIST Definition of Cloud Computing. White
	paper
	-R. Nyrén, A. Edmonds, A. Papaspyrou, and T. Metsch. (2011, April) Open cloud
	computing interface - core. White paper. Open Grid Forum
	-T. Metsch and A. Edmonds. (2011, June) Open cloud computing interface - infrastructure

U5.5 Electives Unit 1: IOT ADAVANCED

U5.5.2 IOT Chain Implementation

Module designation	IOT Advanced
Module level, if applicable	2 nd year of Mechatronics engineering
Code, if applicable	U4.4
Subtitle, if applicable	
Courses, if applicable	IOT Chain Implementation
Semester (s) in which the module is taught	-Semester 5
Person responsible for the module	Dept. Head Dr Emna Rabhi
Lecturer	M Ahmed Boughanmi/M Moez Halaoui
Language	French
Relation to curriculum	Elective Professional module
Type of teaching, contact hours	42 Workshop / Projects
Workload	Total 84 Hours (42 Hours of Self Study)
Credit points	3
Requirements according to the examination regulations	- Minimum attendance rate: 80% of the total contact hours
	>20 % of nonattendance = elimination for exams
Recommended prerequisites	Cloud et sécurité/ systeme embarqué/ linux embarqué
Module objectives/intended learning outcomes	Objectives: -the student must be able to implement an IOT chain by applying all his knowledge of embedded systems and IOT
Content	Project axes:
	The teacher proposes axes of implementation of an IOT chain and leaves the choice to the student
	- Smart city: smart road traffic, smart transport, waste collection, various maps (noise, energy, etc.).
	 Industrial control: measurement, prognosis and prediction of failures, remote troubleshooting.
	 Health: monitoring of biological parameters remotely.
	 Smart agriculture, home automation, playful applications

Study and examination requirements and forms of examination	Evaluation of report, and oral presentation (100%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT)
Reading list	

U5.5 ElectiveUnit 2 : Automotive Embedded System

05.5.1 Electiv	ve Unit 1 Automotive Embedded System
Module designation	Automotive Embedded System
Module level, if applicable	3 rd year of engineering Cycle
Code, if applicable	U5.5
Subtitle, if applicable	-
Courses, if applicable	Automotive Embedded System
Semester (s) in which the module is taught	Semester 5
Person responsible for the module	Dept. Head Emna Rabhi
Lecturer	Dr Lahbib Younes
Language	English
Relation to curriculum	Elective Professional Module
Type of teaching, contact hours	21 Workshop 21 Projects
Workload	Total 84 Hours (42 Hours of Self Study)
Credit points	3
Requirements according to the	-Minimum Attendance rate : 80%
examination regulations	>20% of non-attendance= elimination for exams
Recommended prerequisites	Microcontrollers Architecture
Module objectives/intended learning outcomes	 Objectives: This course provides a comprehensive introduction to Automotive Embedded systems design, implementation and evaluation. Learning Outcomes: At the end of the course, student have the ability to: 1. critically evaluate different hardware implementation strategies and be able to assess their implications on both the functional and non-functional performance of the automotive embedded system 2. critically evaluate the different prototyping methods for design and verification of the automotive control system 3. propose a functional safety strategy for such system 4. Understand and apply principles of discrete control system's analysis and design.

U5.5.1 Elective Unit 1 Automotive Embedded System

Content	 Chapter 1. Introduction to Automotive Embedded Systems Introduction to Automotive Embedded Systems Basic overview on different domains in Automotive Systems Chapter 2. Introduction to Model based Development Overview of CAN & Flexray Protocol Software Development demands in Automotive Industry
	 Introduction to Model based Development in MATLAB Environment Chapter 3. MAAB Guidelines MATLAB Automotive Advisory Board Process Overview Simulation & Code Generation Chapter 4. Introduction to Autosar Autosar Basics
	 Autosar Basics Autosar Software Components & Application Layer Chapter 5. Automotive Functional Safety & ISO26262 - 1 Automotive Functional Safety Concepts Overview of ISO26262
	 Workshop & Projects: Workshop using Matlab- Simulink to run Automotive Application examples: 1.Using a Data Dictionary to Manage the Data for a Fuel Control System 2.Simulate Simple Driving Scenario and Sensor in Unreal Engine Environment 3. Modelling an Automatic Transmission Controller
	Students will work in Laboratory on group base project that will be supervised by the Teacher.
Study and examination requirements and forms of examination	Evaluation of report, and oral presentation (100%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Video projection
Reading list	MathWorks <u>www.mathworks.org</u>

U5.5 ElectiveUnit 2 : Automotive Embedded System

Module designation	Automotive Embedded System
Module level, if applicable	3 rd year of engineering Cycle
Code, if applicable	U5.5
Subtitle, if applicable	-
Courses, if applicable	Autonomous Vehicle Systems
Semester (s) in which the module is taught	Semester 5
Person responsible for the module	Dept. Head Emna Rabhi
Lecturer	Dr Lahbib Younes
Language	English
Relation to curriculum	Elective Professional Module
Type of teaching, contact hours	21 Workshop 21 Projects
Workload	Total 84 Hours (42 Hours of Self Study)
Credit points	3
Requirements according to the examination regulations	-Minimum Attendance rate : 80% >20% of non-attendance= elimination for exams
Recommended prerequisites	Electronics, robotics, Linear algebra, Calculus
Module objectives/intended learning outcomes	Objectives: Introduction to Autonomous Automotive systems Understand car vehicle motion & lateral, Longitudinal control techniques using Matlab-Simulink Models
	 Learning Outcomes: At the end of the course, the student have the ability to: 1. Simulate & Analyse Longitudinal Controller Stanley 2. Simulate & Analyse Lateral Controller Stanley

U5.5.2 Elective Module 2: Autonomous Vehicle System

Content	Contents Chapter 1. Introduction to The Requirements for Autonomy -Driving Tasks -Driving Environment Chapter 2.Vehicle Longitudinal Control - Tracking a speed profile along a fixed path, - Control techniques & Accuracy - Dynamic motions. Chapter 3: Vehicle Lateral Control -Tracking of fixed path -Geometric control model -Predictive Control Model Workshop & Projects: Workshop using Matlab- Simulink to run Controller examples: 1. Longitudinal Controller Stanley 2. Lateral Controller Stanley Students will work in Laboratory on group base project
Study and examination requirements and forms of examination	that will be supervised by the Teacher. Evaluation of report, and oral presentation (100%)
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT) Video projection
Reading list	MathWorks www.mathworks.org

U5.6: Management U5.6.1: Business Intelligence

Module designation	Management
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.6
Subtitle, if applicable	
Courses, if applicable	Business Intelligence
Semester(s) in which the module is taught	Semester 5
Person responsible for the module	Dr Emna RABHI
Lecturer	Aida ben Salem
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	21 hours workshop/ Semester
Workload	Total 42hours/ Semester (21 hours of Self Study)
Credit points	1.5
Requirements according to the examination regulations	 Minimum attendance rate: 80% of the total contact hours >20 % of nonattendance = elimination for exams
Recommended prerequisites	Object Oriented programming, Databases, Numerical Analysis
Module objectives/intended learning outcomes	 Objectives: 1. Understand Business Intelligence and its use in management 2. Learn about Business Intelligence and its components 3. Description of Data Warehouses 4. Understand Decision-making projects and tools

	Chapter I. Introduction to Business Intelligence BI
Content	1. History and genesis
	2. Operational IT vs. Business Intelligence
	3. OnLine Analytical Processing OLAP and OnLine
	,
	Transaction Processing OLTP Applications
	4. Business Intelligence Architecture
	Chapter II: Principle of a Data Warehouse
	1. Interest
	2. Definition
	3. Data modelling
	4. Example
	Chapter III: Data Warehouse DWH Design
	1. Dimensional modelling
	2. Star dimensional modelling
	3. Star DWH Case Study
	4. Dimensional snowflake modelling
	5. Flake DWH Case Study
	6. Operations on dimensional modelling
	7. Decision bus and Constellation
	8. Case study of a decision bus in a DWH
	9. Data store (Data Mart)
	Chapter IV: Feeding a Data Warehouse (ETL)
	1. ETL: Extraction - Transformation - Load
	2. Definition
	3. Design
	4. Tools
	5. Example
	6. Metadata
	Chapter V: Decision-making projects and tools
	1. Business Intelligence project
	2. The actors of a project
	3. Business Intelligence tools
Study and examination requirements and forms of	100 % Workshop/Seminar/ Project evaluation (Oral Exam)
examination	
Media employed	Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT)
	Video projection
-	
Reading list	 Data Science for Business: What you need to know about data mining and data-analytic thinking
	 ✓ Data mining et statistique décisionnelle, Stéphane Tufféry, 5 janvier 2010

U5.6 : Management

U5.6.2 : Industrial Logistics

Module designation	Management
Module level, if applicable	Year 3, Semester 1
Code, if applicable	U5.6
Subtitle, if applicable	-
Courses, if applicable	Industrial Logistics
Semester (s) in which the module is taught	Semester 1
Person responsible for the module	Dr Emna RABHI
Lecturer	Mme Rihab Mechmech
Language	French
Relation to curriculum	Compulsory module ,
Type of teaching, contact hours	21 hours for Workshop in Lab/ semester
Workload	Total 42hours/ Semester (21 hours of Self Study)
Credit points	1.5
Requirements according to the	- Minimum attendance rate: 80% of the total contact hours
examination regulations	>20 % of nonattendance = elimination for exams
Recommended prerequisites	-
Module objectives/intended learning outcomes	 Objectives: To identify the basic concepts: logistics, supply chain and supply chain management. To optimize inventory management. To optimize logistics costs. To evaluate the logistics process within a company. To optimize the industrial jobs scheduling and allocation throughout the production process. Learning Outcomes: Identify the different logistics costs. Optimize the inventory logistics flows. Propose a logistic dashboard. Schedule the various jobs in an industrial process. Optimize production objectives (the total production time, delays, etc.) Optimize the industrial resources exploitation.

Classroom Lecture and Guided Work
 1 General Introduction to Industrial Logistics Basic concepts. Supply chain management. Supply chain performance. Decision-making process. EDI-supply chain. 2 Inventory management Basic concepts. Inventory control. Inventory valuation methods. The different logistic storage costs. Inventory management models. tutorials, group work, and exercises. 3 Logistics Dashboard Basic concepts. Characteristics of a dashboard (key performance indicators "KPIs"). Tutorials (case studies). 4 Scheduling problems- Single machine and parallel machines Basic concepts (objectives and constraints). Real-life examples. Complexity of scheduling problems. Scheduling schemes. Priority rules (Software: Lekin) and mathematical models.
-Tutorials and Practical exercises.
Written Mid-term Exam (40%)/ Final Exam (60%)
Course Material (Hard/ Soft copy) for Classroom & Online (Moodle ULT)
Video projection
 Yves Pimor, Michel Fender, La logistique : production, distribution, soutien ;5^{ème} édition. LA LOGISTIQUE, BARBARA LYONNET ET MARIE-PASCALE SENKEL Ordonnancement, Patrick Esquirol et Pierre Lopez, 1999,